

# Project 1: Fork and Exec

Consult the submit server for deadline date and time

You will implement the `Fork()` and `Exec()` operations, preserving the semantics of `Pipe()` across both: that both parent and child have the same file descriptors attached to the pipe, both parent and child may read and write to the pipe, and the `exec'd` program inherits the file descriptors of the process.

The primary goal of this assignment is to develop an understanding of the process control block (`struct Kernel_Thread`) and user context structures (`struct User_Context`).

## 1 Desired Semantics

In general, `Fork()` here should work as described in the man page for `fork` (`fork(2)`), with the following exceptions and specifics. `GeekOS` lacks many of the features that “real” `fork()` must make decisions about, such as signal inheritance, what to do about multiple threads, and resource limits.

- `Fork()` must return the child’s pid in the parent and zero in the child. The Child’s pid must be new and sequential. (Do not worry about overflow/wrap.)
- Global variables must start out the same, but each process updates its own copy.
- The stack should appear the same at the point of the `Fork` call, but each process has its own copy.
- File descriptions are shared: when either process updates the position in a file, that should update the position as seen by the other process.
- `Fork()` should return `ENOMEM` if a memory allocation fails, which it will if `fork` is called enough times.

### 1.1 Repository

The `projects.h` file includes flags that cause different `TODO()` macros in the distribution to fire.

### 1.2 Process Creation

The existing scheme for creating new processes is the `Spawn()` function. `Spawn()` is a bit like the Windows `CreateProcess` function, which creates a new process with a program name to implement. It does *everything*, which means it contains the core of both `Fork()` and `Exec()`. However, `Spawn` lacks a facility for creating the intermediate state: copying the address space from parent to child. It also lacks the functionality we seek with inheriting file descriptors. Finally, `Spawn()` creates the new process with an empty context rather than at the point of a `fork`. We’ll discuss these new features in a bit more detail than those old features you’ll find already in the code.

Each process is represented by a “`struct Kernel_Thread`” typically named “`kthread`” as a local variable. There are kernel processes, which are really threads inside the kernel, since they all share the same address space. User processes have a “`userContext`” pointer set in the `kthread`. The `userContext` contains the stuff unique to user processes: their own address spaces, file descriptors, etc.

To `Fork()`, a new `kthread` must be created. Unlike in `Spawn()`, the contents of memory should not be the result of loading a program file, it should be a copy of the memory of the parent. In a real operating system with paging, this copy would occur lazily (and efficiently) via `copy-on-write`.

### 1.3 Copying the address space

Look in `userseg.c` to note how a user context can be created. The kernel has `mempcpy()`. This one is pretty easy.

### 1.4 Inheriting file descriptors

Copy the file descriptor array from parent to child, then iterate over this list incrementing the reference count of each file. Most file descriptors will reference NULL.

### 1.5 Register Context

When a function makes a system call, the user process's registers are pushed onto the kernel's per-process stack. The kernel's stack is in the kthread "stackPage", while the stack pointer is `esp`. When cloning a process, the child should have substantially the same kernel stack, to represent substantially the same registers (one will be different).

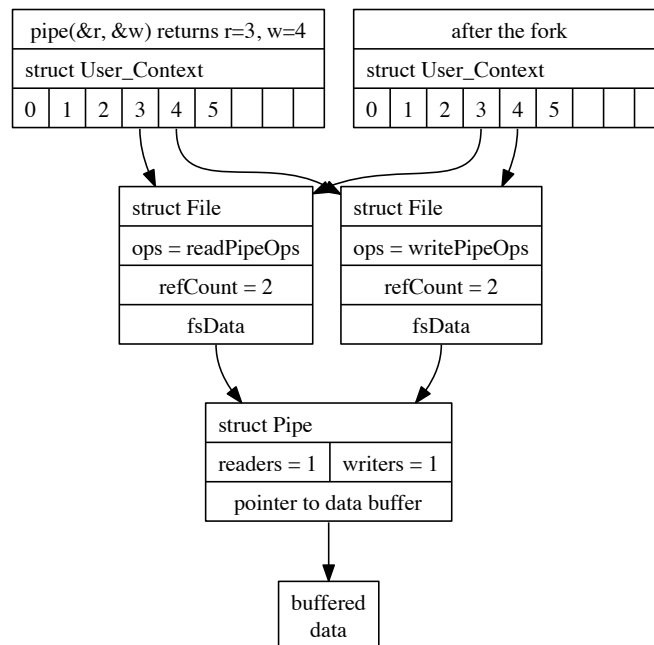


Figure 1: Illustration of the file descriptor table (top), where entries point to struct File objects, after Fork(). There are two struct File objects for the pipe. The pipe object must track whether there are any readers or writers and keep buffered data, the File object must track how many processes (kthreads) hold a reference to the File.

### 1.6 Synchronization

With Fork(), particularly with SMP, comes the possibility that two of your processes may be running at the same time. If not careful about preventing concurrent access to the same operations, you may create a race condition that will cause data corruption at random; alternately, you may cause a deadlock condition - no processes can make progress.

In this section, I use “process” and “kernel thread” interchangeably, since the code you’re writing is in the kernel, running in a thread (they share an address space in the kernel), on behalf of a process.

### 1.6.1 The hammer

`Deprecated_Disable_Interrupts()` and `Deprecated_Enable_Interrupts()` grab and release the “big” global lock. `Deprecated_Begin_Int_Atomic()` and `Deprecated_End_Int_Atomic()` grab and release the global lock if it is not already held, allowing routines to be called with or without the lock.

As you can tell, these are “deprecated,” which means not to use them in new code.

These routines will prevent interrupts from occurring on the current processor and grab a lock that prevents the interrupt handler from running on any other processor. That means that the timer interrupt will eventually block execution of the other processor’s activity.

Any process waiting for the global lock spins, with interrupts disabled, expecting the code on the other processor to release the global lock. (That is, it would be bad if the other processor is somehow not going to release the global lock.)

### 1.6.2 The knife

`Mutex_Lock` and `Mutex_Unlock` (see `synch.c`) will put a blocked thread on a wait queue until the lock is released. See, for example, the use of mutexes in `vfs.c` to guard the list of file systems.

Using a mutex requires that interrupts be *enabled*. That is, the calling code expecting to request a mutex has to know that it might not get it immediately. Another thread might need to run, and data structures that might be shared should be in a consistent state.

For concurrency associated with shared resources (such as a pipe) owned by processes that may be suspended (especially user processes), a mutex is probably best.

### 1.6.3 The rock

The spinlock is quite possibly not a good synchronization tool, but it appears in `geekos` and may be useful for guarding data structures for brief periods efficiently.

Each list in `geekos` (see `list.h`) is guarded by a spinlock. This spinlock is meant to defend the list against accidental concurrent access, but because of its limitations, may not be appropriate protection. In particular, if a thread holding a spinlock is interrupted and put back on the ready queue, any later thread would just spin trying to get the spinlock and may not let the interrupted thread back onto the processor to release it. Ensure that interrupts are disabled (the non-deprecated version) before acquiring a spinlock.

Simple list operations automatically grab and release that lock. Some operations, such as “get next in list” expect the lock to be held. Consult the `list.h` source to determine which functions are appropriate for you.

From <http://en.wikipedia.org/wiki/Spinlock>,

Because they avoid overhead from operating system process rescheduling or context switching, spinlocks are efficient if threads are only likely to be blocked for a short period. For this reason, spinlocks are often used inside operating system kernels. However, spinlocks become wasteful if held for longer durations, as they may prevent other threads from running and require rescheduling. The longer a lock is held by a thread, the greater the risk is that the thread will be interrupted by the OS scheduler while holding the lock. If this happens, other threads will be left “spinning” (repeatedly trying to acquire the lock), while the thread holding the lock is not making progress towards releasing it. The result is an indefinite postponement until the thread holding the lock can finish and release it. This is especially true on a single-processor system, where each waiting thread of the same priority is likely to waste its quantum (allocated time where a thread can run) spinning until the thread that holds the lock is finally finished.

## 1.7 Rules and Hints

Follow the path of `Spawn()` and determine which features are part of `Exec()` and which features are part of `Fork()`. Most everything in you need is already present.

Alter 'struct File' to add a reference count. Alter Open(), Fork(), and Close() to set, increment, and decrement this reference count.

You may modify any function needed, regardless of whether a TODO\_P(PROJECT\_FORK) macro is present. (You may need to modify other functions.)

Most changes will be in pipe.c and syscall.c, possibly in user.c or userseg.c.

## 2 Tests

There are a few public tests: fork-p1, forkipipe, and forkexec. They are intended to cover the bulk of the functionality described here.

Expect "secret" tests to exercise other behavior described in this handout. "Secret" tests are likely to cover bizarre mistakes such as failing to replicate the data segment and failing to count references for pipes.

There is a "forkbomb" test which may be passed by containing the bomb: either it continues to fork indefinitely or all processes exit and return to a working shell.