

Concurrency

- Exam 1
- 26 - Concurrency
- 27 - Overview, and POSIX threads (pthreads)
- 28 - Locks
- 29 - Concurrent Data Structures
- 30 Condition Variables
- 31 - Semaphores
- 32 - Common Problems
- 33 - Event-Based Concurrency

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Concurrent Data *counters*

```
1     typedef struct __counter_t {
2         int value;
3     } counter_t;
4
5     void init(counter_t *c) {
6         c->value = 0;
7     }
8
9     void increment(counter_t *c) {
10        c->value++;
11    }
12
13    void decrement(counter_t *c) {
14        c->value--;
15    }
16
17    int get(counter_t *c) {
18        return c->value;
19    }
```

- simple, but not correct

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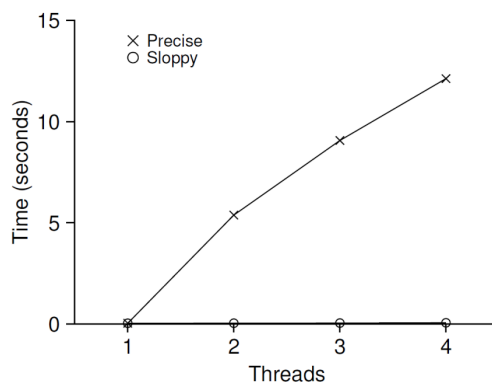
Concurrent Data *counters*

```
1     typedef struct __counter_t {
2         int value;
3         pthread_lock_t lock;
4     } counter_t;
5
6     void init(counter_t *c) {
7         c->value = 0;
8         Pthread_mutex_init(&c->lock, NULL);
9     }
10
11    void increment(counter_t *c) {
12        Pthread_mutex_lock(&c->lock);
13        c->value++;
14        Pthread_mutex_unlock(&c->lock);
15    }
16
17    void decrement(counter_t *c) {
18        Pthread_mutex_lock(&c->lock);
19        c->value--;
20        Pthread_mutex_unlock(&c->lock);
21    }
22
23    int get(counter_t *c) {
24        Pthread_mutex_lock(&c->lock);
25        int rc = c->value;
26        Pthread_mutex_unlock(&c->lock);
27        return rc;
28    }
```

- correct, but not performant (research as late as 2010)

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Concurrent Data *counter performance*



**Performance of
Traditional vs. Sloppy Counters**
(Threshold of Sloppy, S , is set to 1024)

- sloppiness can be useful....

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Concurrent Data *sloppy (approximate) counters*

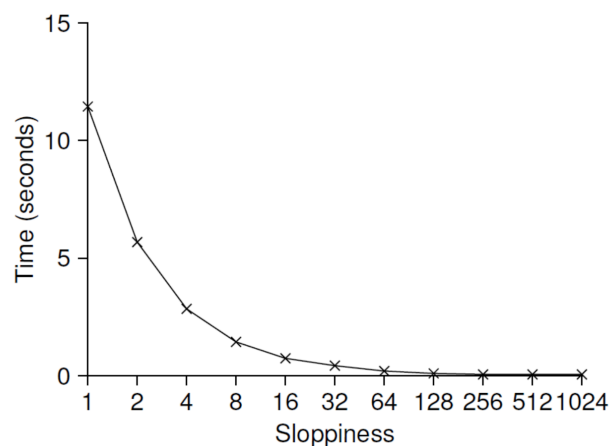
- sloppiness can be useful....
 - each core has local counter
 - threads update local counter
 - periodically transfer counts to a *global* counter

Time	L_1	L_2	L_3	L_4	G
0	0	0	0	0	0
1	0	0	1	1	0
2	1	0	2	1	0
3	2	0	3	1	0
4	3	0	3	2	0
5	4	1	3	3	0
6	5 \rightarrow 0	1	3	4	5 (from L_1)
7	0	2	4	5 \rightarrow 0	10 (from L_4)

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Concurrent Data *sloppy (approximate) counters*

- importance of threshold s
 - low s : poor performance, global count quite accurate
 - high s : good performance, global count quite inaccurate



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Concurrent Data *linked lists*

```
1 // basic node structure
2 typedef struct __node_t {
3     int key;
4     struct __node_t *next;
5 } node_t;
6
7 // basic list structure (one used per list)
8 typedef struct __list_t {
9     node_t *head;
10    pthread_mutex_t lock;
11 } list_t;
12
13 void List_Init(list_t *L) {
14     L->head = NULL;
15     pthread_mutex_init(&L->lock, NULL);
16 }
17
(Cont.)
```

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Concurrent Data *linked lists*

```
18 int List_Insert(list_t *L, int key) {
19     pthread_mutex_lock(&L->lock);
20     node_t *new = malloc(sizeof(node_t));
21     if (new == NULL) {
22         perror("malloc");
23         pthread_mutex_unlock(&L->lock);
24         return -1; // fail
25     }
26     new->key = key;
27     new->next = L->head;
28     L->head = new;
29     pthread_mutex_unlock(&L->lock);
30     return 0; // success
31 }
32
33 int List_Lookup(list_t *L, int key) {
34     pthread_mutex_lock(&L->lock);
35     node_t *curr = L->head;
36     while (curr) {
37         if (curr->key == key) {
38             pthread_mutex_unlock(&L->lock);
39             return 0; // success
40         }
41         curr = curr->next;
42     }
43     pthread_mutex_unlock(&L->lock);
44     return -1; // failure
45 }
```

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Concurrent Data *linked lists*

- Works!
 - but slow
 - also error-prone:
 - if `malloc()` fails, code must release the lock
 - solution: lock and release *only around crit section*

```
6     void List_Insert(list_t *L, int key) {
7         // synchronization not needed
8         node_t *new = malloc(sizeof(node_t));
9         if (new == NULL) {
10            perror("malloc");
11            return;
12        }
13        new->key = key;
14
15        // just lock critical section
16        pthread_mutex_lock(&L->lock);
17        new->next = L->head;
18        L->head = new;
19        pthread_mutex_unlock(&L->lock);
20    }
```

Concurrent Data *scaling linked lists*

- Hand-over-hand locking (*lock coupling*)
 - lock per node
 - traverse the list:
 - grab next node's lock
 - release current node's lock
 - evaluation:
 - concurrency: *great!*
 - performance: *horrible!*
- Michael and Scott *concurrent queues*:
 - one lock for head
 - one lock for tail
 - and a dummy node to separate head and tail operations

Concurrent Data *concurrent queues*

```
1     typedef struct __node_t {
2         int          value;
3         struct __node_t *next;
4     } node_t;
5
6     typedef struct __queue_t {
7         node_t *head;
8         node_t *tail;
9         pthread_mutex_t headLock;
10        pthread_mutex_t tailLock;
11    } queue_t;
12
13    void Queue_Init(queue_t *q) {
14        node_t *tmp = malloc(sizeof(node_t));
15        tmp->next = NULL;
16        q->head = q->tail = tmp;
17        pthread_mutex_init(&q->headLock, NULL);
18        pthread_mutex_init(&q->tailLock, NULL);
19    }
20
21    (Cont.)
```

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Concurrent Data *concurrent queues*

```
21     void Queue_Enqueue(queue_t *q, int value) {
22         node_t *tmp = malloc(sizeof(node_t));
23         assert(tmp != NULL);
24
25         tmp->value = value;
26         tmp->next = NULL;
27
28         pthread_mutex_lock(&q->tailLock);
29         q->tail->next = tmp;
30         q->tail = tmp;
31         pthread_mutex_unlock(&q->tailLock);
32     }
33
34     int Queue_Dequeue(queue_t *q, int *value) {
35         pthread_mutex_lock(&q->headLock);
36         node_t *tmp = q->head;
37         node_t *newHead = tmp->next;
38         if (newHead == NULL) {
39             pthread_mutex_unlock(&q->headLock);
40             return -1; // queue was empty
41         }
42         *value = newHead->value;
43         q->head = newHead;
44         pthread_mutex_unlock(&q->headLock);
45         free(tmp);
46         return 0;
47     }
```

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Condition variables *one BAD implementation*

- Waiting:

```
while(initialized == 0)
    ; // spin
```

- Signaling:

```
initialized = 1;
```

- spinlock wastes CPU
- does not include lock synchronization
- source of many, many bugs

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Condition Variables *parent waiting on child*

A Parent Waiting For Its Child

```
1     void *child(void *arg) {
2         printf("child\n");
3         // XXX how to indicate we are done?
4         return NULL;
5     }
6
7     int main(int argc, char *argv[]) {
8         printf("parent: begin\n");
9         pthread_t c;
10        Pthread_create(&c, NULL, child, NULL); // create child
11        // XXX how to wait for child?
12        printf("parent: end\n");
13        return 0;
14    }
```

What we would like to see here is:

```
parent: begin
child
parent: end
```

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Condition Variables *parent waiting on child*

```
1     volatile int done = 0;
2
3     void *child(void *arg) {
4         printf("child\n");
5         done = 1;
6         return NULL;
7     }
8
9     int main(int argc, char *argv[]) {
10        printf("parent: begin\n");
11        pthread_t c;
12        Pthread_create(&c, NULL, child, NULL); // create child
13        while (done == 0)
14            ; // spin
15        printf("parent: end\n");
16        return 0;
17    }
```

- Correct, but:
 - wildly inefficient
 - sometimes incorrect

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Condition Variables *parent waiting on child*

- Condition variable:
 - `signal()` that condition is true
 - `wait()` on condition to become true
- `pthread_cond_wait`:
 - put the calling thread to sleep
 - releases the mutex
 - wait for signal from some other thread
 - re-acquire mutex
- `pthread_cond_signal`:
 - unblock *at least one* of the threads blocked on the conditional variable
 - ??

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Condition Variables *parent waiting on child*

```
2 pthread_mutex_t m = PTHREAD_MUTEX_INITIALIZER;
3 pthread_cond_t c = PTHREAD_COND_INITIALIZER;
4
5 void thr_exit() {
6     pthread_mutex_lock(&m);
7     pthread_cond_signal(&c);
8     pthread_mutex_unlock(&m);
9 }
10
11
12 void *child(void *arg) {
13     printf("child\n");
14     thr_exit();
15     return NULL;
16 }
17
18 void thr_join() {
19     pthread_mutex_lock(&m);
20     pthread_cond_wait(&c, &m);
21     pthread_mutex_unlock(&m);
22 }
23
24
25 int main(int argc, char *argv[]) {
26     printf("parent: begin\n");
27     pthread_t p;
28     pthread_create(&p, NULL, child, NULL);
29     thr_join();
30     printf("parent: end\n");
31     return 0;
32 }
```

no

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Condition Variables *parent waiting on child*

```
1   int done = 0;
2   pthread_mutex_t m = PTHREAD_MUTEX_INITIALIZER;
3   pthread_cond_t c = PTHREAD_COND_INITIALIZER;
4
5   void thr_exit() {
6       pthread_mutex_lock(&m);
7       done = 1;
8       pthread_cond_signal(&c);
9       pthread_mutex_unlock(&m);
10  }
11
12  void *child(void *arg) {
13      printf("child\n");
14      thr_exit();
15      return NULL;
16  }
17
18  void thr_join() {
19      pthread_mutex_lock(&m);
20      while (done == 0)
21          pthread_cond_wait(&c, &m);
22      pthread_mutex_unlock(&m);
23  }
24
25  int main(int argc, char *argv[]) {
26      printf("parent: begin\n");
27      pthread_t p;
28      pthread_create(&p, NULL, child, NULL);
29      thr_join();
30      printf("parent: end\n");
31      return 0;
32  }
```

yes!

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Condition variables *continued*

- **Waiting:**

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t  init = PTHREAD_COND_INITIALIZER;

pthread_mutex_lock(&lock);
while (initialized == 0)
    pthread_cond_wait(&init, &lock);
pthread_mutex_unlock(&lock);
```

- the wait call releases the lock when the thread sleeps
- the wait call re-acquires the lock when thread awakened

- **Signaling:**

```
pthread_mutex_lock(&lock);
initialized = 1;
pthread_cond_signal(&init);
pthread_mutex_unlock(&lock);
```

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Producer-Consumer *flawed take 1*

```
int loops; // must initialize somewhere...
cond_t cond;
mutex_t mutex;

void *producer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);           // p1
        if (count == 1)                       // p2
            Pthread_cond_wait(&cond, &mutex); // p3
        put(i);                               // p4
        Pthread_cond_signal(&cond);          // p5
        Pthread_mutex_unlock(&mutex);        // p6
    }
}

void *consumer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);           // c1
        if (count == 0)                       // c2
            Pthread_cond_wait(&cond, &mutex); // c3
        int tmp = get();                      // c4
        Pthread_cond_signal(&cond);          // c5
        Pthread_mutex_unlock(&mutex);        // c6
        printf("%d\n", tmp);
    }
}
```

Figure 30.8: Producer/Consumer: Single CV And If Statement

Assume buffer size 1,
initially empty,
2 consumers, 1 producer

c₁
c₁
c₃ *block*

p1
p2
p4
p5 *c₁ unblocked*
p6
p1
p2
p3

c₂
c₂
c₄
c₅ *c₁ unblocked*
c₆
c₂
c₂
c₃

c₄ *crash*

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Producer-Consumer *flawed take 1*

- What was the problem?
 - between c₁ becoming ready, and calling `get()`, the world changed
- Getting *signaled()* is only a hint that the world has changed
 - need to check again
 - and do so atomically w/ the `get()`
- Semantics:
 - this is *Mesa* semantics
 - *Hoare* semantics imply a signaled thread runs immediately

Most systems assume Mesa semantics. You should too. Even if not strictly necessary.

Producer-Consumer *flawed take 2*

```
int loops;
cond_t cond;
mutex_t mutex;
```

Assume buffer size 1,
initially empty,
2 consumers, 1 producer

*But there's still
a bug....*

```
void *producer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);           // p1
        while (count == 1)                   // p2
            Pthread_cond_wait(&cond, &mutex); // p3
        put(i);                               // p4
        Pthread_cond_signal(&cond);          // p5
        Pthread_mutex_unlock(&mutex);        // p6
    }
}

void *consumer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);           // c1
        while (count == 0)                   // c2
            Pthread_cond_wait(&cond, &mutex); // c3
        int tmp = get();                      // c4
        Pthread_cond_signal(&cond);          // c5
        Pthread_mutex_unlock(&mutex);        // c6
        printf("%d\n", tmp);
    }
}
```

c1
c2
c3 *blocks*

c21
c22
c23 *blocks*

p1, p2, p4
p5 *c1 unblocked*
p6
p1
p2
p3 *p blocks*

c12
c14
c15 *c2 unblocked*
...
c13 *c1 blocks*

c22
c23 *c2 blocks*

everyone blocked!

Figure 30.10: Producer/Consumer: Single CV And While

Producer-Consumer *correct take 3*

```
cond_t empty, fill;
mutex_t mutex;
```

```
void *producer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);           // p1
        while (count == 1)                   // p2
            Pthread_cond_wait(&empty, &mutex); // p3
        put(i);                               // p4
        Pthread_cond_signal(&fill);          // p5
        Pthread_mutex_unlock(&mutex);        // p6
    }
}

void *consumer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);           // c1
        while (count == 0)                   // c2
            Pthread_cond_wait(&fill, &mutex); // c3
        int tmp = get();                      // c4
        Pthread_cond_signal(&empty);         // c5
        Pthread_mutex_unlock(&mutex);        // c6
        printf("%d\n", tmp);
    }
}
```

c1
c2
c3 *blocks*

c21
c22
c23 *blocks*

p1, p2, p4
p5 *c1 unblocked*
p6
p1
p2
p3 *p blocks*

c12
c14
c15 *p unblocked*

c22
c23 *blocks*

all good!

Figure 30.12: Producer/Consumer: Two CVs And While

Assume initially no memory available.

Memory allocation *covering condition*

```
// how many bytes of the heap are free?
int bytesLeft = MAX_HEAP_SIZE;

// need lock and condition too
cond_t c;
mutex_t m;

void *
allocate(int size) {
    Pthread_mutex_lock(&m);
    while (bytesLeft < size)
        Pthread_cond_wait(&c, &m);
    void *ptr = ...; // get mem from heap
    bytesLeft -= size;
    Pthread_mutex_unlock(&m);
    return ptr;
}

void free(void *ptr, int size) {
    Pthread_mutex_lock(&m);
    bytesLeft += size;
    Pthread_cond_signal(&c); // whom to signal??
    Pthread_mutex_unlock(&m);
}
```

```
ta alloc(100) blocks
tb alloc(10) blocks
tc free(50)
```

Which thread to wake?

- wake 'em all!
- might be inefficient
- but correct

```
pthread_cond_broadcast()
```

"covering condition"

Figure 30.15: **Covering Conditions: An Example**